

1.2 Autonomous Homogeneous Systems (A constant matrix, $g \equiv 0$)

Theorem (Existence & Uniqueness of IVPs):

Let $A \in \mathbb{C}^{n \times n}$, $x_0 \in \mathbb{C}^n$. Then the IVP

$$\dot{x}(t) = Ax(t), \quad x(t_0) = x_0 \quad (1.4)$$

has a unique solution.

Proof (sketch):

a) Existence: Define the matrix exponential for $Y \in \mathbb{C}^{n \times n}$

$$\exp(tY) = \sum_{k=0}^{\infty} \frac{1}{k!} (tY)^k \equiv I + tY + \frac{t^2}{2!} Y^2 + \dots$$

Property 1: $\exp(tY)$ converges $\forall t \in \mathbb{R}$.

Property 2: $\frac{d}{dt} \exp(tY) = Y \exp(tY) = \exp(tY) Y$

Define $x(t) = \exp((t-t_0)A) x_0$

Then $x(t_0) = \exp(0 \cdot A) x_0 = I x_0 = x_0$

and $\dot{x}(t) = A \exp((t-t_0)A) x_0 = Ax(t)$.

Hence $x(t)$ solves the IVP (1.4).

Note: It is difficult to compute the matrix exponential $\exp(tA)$ explicitly (discussed later).

b) Uniqueness: let $y(t)$ be another solution of (1.4)

$$\text{Consider } h(t) = x(t) - y(t)$$

$$\text{Then } \dot{h}(t) = \dot{x}(t) - \dot{y}(t) = Ax(t) - Ay(t) = Ah(t)$$

$$\therefore \dot{h}(t) = Ah(t) \quad \text{and} \quad h(t_0) = 0.$$

We wish to show $h(t) \equiv 0$. Suffice to show $\|h(t)\| = 0$.

$$\text{For } h(t) = \begin{pmatrix} h_1(t) \\ \vdots \\ h_n(t) \end{pmatrix} \in \mathbb{C}^n, \quad \|h\| := (|h_1|^2 + \dots + |h_n|^2)^{1/2}$$

$$\text{Now, } \frac{dh(s)}{ds} = Ah(s) \Rightarrow \int_{t_0}^t \frac{dh}{ds} ds = \int_{t_0}^t Ah(s) ds$$

$$\text{i.e. } h(t) - \underbrace{h(t_0)}_0 = \int_{t_0}^t Ah(s) ds$$

$$\therefore 0 \leq \|h(t)\| = \left\| \int_{t_0}^t Ah(s) ds \right\| \leq \int_{t_0}^t |A| \|h(s)\| ds \quad (*)$$

for $t \geq t_0$

$$\text{where } |A| := \max_{z \neq 0} \frac{\|Az\|}{\|z\|} (= \text{constant} > 0)$$

Let $G(t) = \int_{t_0}^t |A| \|h(s)\| ds$ then $\frac{dG}{dt} = |A| \|h(t)\|$

and (*) becomes $\frac{1}{|A|} \frac{dG(t)}{dt} - G(t) \leq 0$.

The LHS has integrating factor I.F. = $\int_{t_0}^t -|A| ds$
 $e^{-|A|(t-t_0)}$

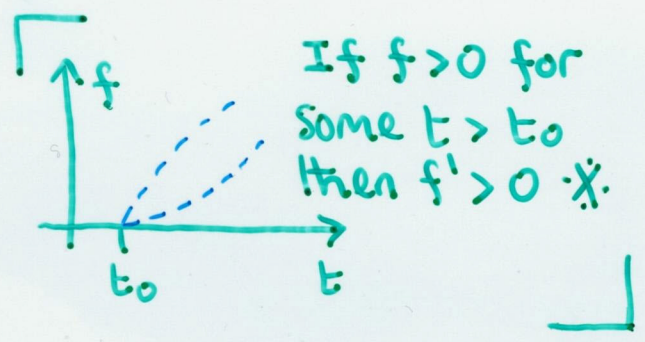
= $e^{-(t-t_0)|A|}$ since $|A|$ is a constant, and hence

can be written as $\frac{d}{dt} \left(\underbrace{e^{-(t-t_0)|A|} G(t)}_{f(t)} \right) \leq 0$

Introduce $f(t) := e^{-(t-t_0)|A|} \int_{t_0}^t |A| \|h(s)\| ds$

satisfies $f(t_0) = 0, \left. \begin{matrix} f(t) \geq 0 \\ f'(t) \leq 0 \end{matrix} \right\}$ for $t \geq t_0$.

Hence $f(t) \equiv 0$ for $t \geq t_0$.



Hence $G(t) \equiv 0$ for $t \geq t_0$

and (*) gives

$$0 \leq \|h(t)\| \leq 0 \quad \forall t \geq t_0 \quad \text{i.e.} \quad \|h(t)\| \equiv 0 \quad \forall t \geq t_0.$$

A similar argument holds for $t \leq t_0$ and thus $\|h(t)\| = 0 \quad \forall t \in \mathbb{R}$ i.e. $h(t) \equiv 0$. □

Definition:

The vector functions $y_i: I \rightarrow \mathbb{C}^n$ $i=1, \dots, m$ with $I \subset \mathbb{R}$ some interval are called

linearly independent on I if for constants $c_i \in \mathbb{C}$

$$\sum_{i=1}^m c_i y_i(t) = 0 \quad \forall t \in I \Rightarrow c_1 = c_2 = \dots = c_m = 0$$

The functions y_i are linearly dependent if they are not linearly independent i.e. if \exists constants c_1, \dots, c_m not all zero s.t. $\sum_{i=1}^m c_i y_i(t) = 0 \quad \forall t \in I$.

Example: let $I = [0, 1]$, $y_1(t) = \begin{pmatrix} e^t \\ t e^t \end{pmatrix}$, $y_2(t) = \begin{pmatrix} 1 \\ t \end{pmatrix}$.
Are y_1, y_2 lin. indep. on I ?

Solution: Answer is yes. Argue by contradiction:

Assume y_1, y_2 are not lin. indep.

Then $\exists c_1, c_2$ not both zero s.t.

$$c_1 y_1(t) + c_2 y_2(t) = 0 \quad \forall t \in I$$

$$\text{i.e. } \begin{aligned} c_1 e^t + c_2 &= 0 \\ c_1 t e^t + c_2 t &= 0 \end{aligned} \quad \forall t \in I.$$

$$\left. \begin{aligned} \text{let } t=0: & \quad c_1 + c_2 = 0 \\ \text{let } t=1: & \quad c_1 e + c_2 = 0 \end{aligned} \right\} c_1 = c_2 = 0 \quad \times$$

Hence y_1, y_2 are lin. indep. □

Notes:

1. $y_1(t) = e^t y_2(t)$ i.e. $y_1(t)$ is not a constant multiple of $y_2(t) \forall t \in I$.

Thus $y_1(t), y_2(t)$ can't be lin. dep.

2. General Principle: To show linear independence assume linear dependence and seek a contradiction.